1.2V, 10A, 300kHz, Hysteretic Synchronous **Step-Down Controller Evaluation Board** 

The Future of Analog IC Technology

### DESCRIPTION

The EV2905-K-01A is the evaluation board for the MP2905EK, a hysteretic synchronous stepdown controller. It offers a very compact solution to achieve 1.2V, 10A continuous output current from a 10.8V to 13.2V input voltage range over a wide operation input voltage. An adjustable soft-start prevents inrush current at turn-on.

Hysteretic voltage control can provide fast transient without any loop compensation. Full protection features include OCP, output OVP, thermal shut down.

The EV2905-K-01A frequency is approximately 300kHz (12V input). Peak Current limit is set at 15A. The efficiency is up to 90% (12V input) with the supplied components.

## **ELECTRICAL SPECIFICATIONS**

Parameter	Symbol	Value	Units
Input Voltage	$V_{IN}$	10.8 - 13.2V	V
Output Voltage	$V_{OUT}$	1.2	V
Load Current	I <sub>OUT</sub>	10 <sup>(1)</sup>	Α

#### **FEATURES**

- 10A Output Current, 1.2V Output Voltage
- Programmable Soft-Start
- **Hiccup Current Limit and Thermal** Shutdown
- Monotonic Startup into Prebias Output
- Startup Overvoltage Protection
- Enable/Shutdown

#### **APPLICATIONS**

- Motherboard Power Supplies
- AGP and PCI-Express Power Supplies
- **Graphic-Card Power Supplies**
- **Set-Top Boxes**
- Point-of-Load Power Supplies

Circuit can work up to about 10A over a wide input voltage range. This EVB shows the performance at 12V input. So the frequency and current limit are designed for the 12V application

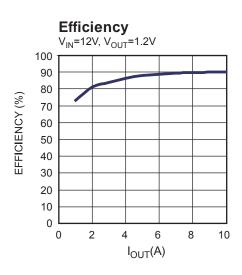
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#### EV2905-K-01A EVALUATION BOARD

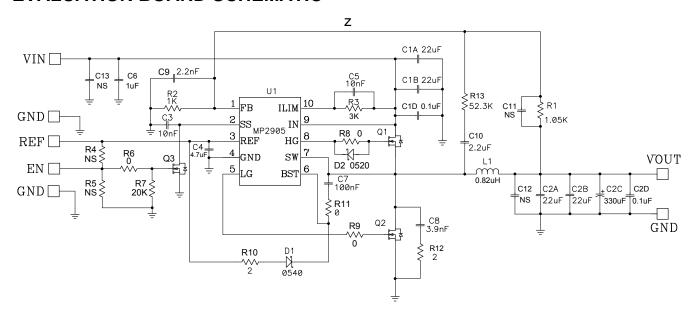


(L x W x H) 2.5" x 2.5" x 0.63" (6.3cm x 6.3cm x 1.6cm)

Board Number	MPS IC Number		
EV2905-K-01A	MP2905EK		



# **EVALUATION BOARD SCHEMATIC**





# **EV2905-K-01A BILL OF MATERIALS**

Qty	RefDes	Value	Description	Package	Manufacturer	Manufacturer P/N
2	C1A,C1B	22µF	Ceramic Cap, X5R, 25V	1210	muRata	GRM32ER61E226KE15L
2	C2A,C2B	22µF	Ceramic Cap, X5R, 16V	1210	muRata	GRM32ER61C226KE20L
1	C2C	330µF	Poscap, 6.3V	Poscap	Sanyo	6TPE330MIL
2	C1D,C2D	0.1µF	Ceramic Cap, X7R, 25V	0603	muRata	GRM188R71E104KA01D
2	C3,C5	10nF	Ceramic Cap, X7R, 50V	0603	muRata	GRM188R71H103KA01D
1	C4	4.7µF	Ceramic Cap, X5R, 6.3V	0603	muRata	GRM188R60J475KE19D
1	C6	1µF	Ceramic Cap, X7R, 25V	0603	muRata	GRM188R71E105KA12D
1	C7	0.1µF	Ceramic Cap, X7R, 50V	0603	muRata	GRM188R71H104KA93D
1	C8	3.9nF	Ceramic Cap, X7R, 50V	0603	muRata	GRM188R71H392KA01D
1	C9	2.2nF	Ceramic Cap, X7R, 50V	0603	muRata	GRM1885R71H222A01D
1	C10	2.2µF	Ceramic Cap, X7R, 10V	0603	muRata	GRM188R71A225KE15D
	C11	NS				
	C12,C13	NS				
1	R1	1.05kΩ	Film Res, 1%	0603	ROYAL	RL0603FR-071K05L
1	R2	1kΩ	Film Res, 1%	0603	ROYAL	RL0603FR-071KL
1	R3	3kΩ	Film Res, 1%	0603	ROYAL	RL0603FR-03KL
	R4,R5	NS				
4	R6,R8 R9,R11	0Ω	Film Res, 1%	0603	Yageo	RC0603FR-070RL
1	R7	20kΩ	Film Res, 1%	0603	ROYAL	RL0603FR-0720KL
2	R10,R12	2Ω	Film Res, 1%	0603	Yageo	RL0603FR-072RL
1	R13	52.3kΩ	Film Res, 1%	0603	ROYAL	RL0603FR-0752K3L
1	D1		B0540W,40V,0.5A	SOD123	Diodes	B0540W
1	D2		B0520LW-7- F,20V,0.5A	SOD323	Diodes	B0520LW-7-F
1	L1	0.82μΗ	Inductor,Rated current=27A,Saturation current=35A,DCR=0.9 $m\Omega$	SMT	Wruth	744355182
2	Q1,Q2		AM7432N,30V,27A,Rd s_on=4.9mΩ@4.5Vgs, Qg=25nC,tr=13ns,tf=43 ns@4.5Vgen	PowerPAK SO-8	Analog Power	AM7432N
1	Q3		2N7002(60V,115mA)	SOT-23	Diodes	2N7002(60V,115mA)
1	U1	MP2905	Synchronous Step-Down Controller	MSOP10	MPS	MP2905EK

# PRINTED CIRCUIT BOARD LAYOUT

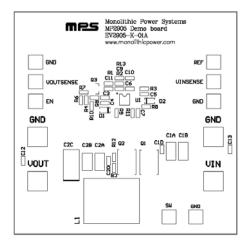


Figure 1—Top Silk Layer

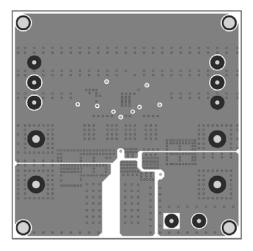


Figure 3—Inner 1 Layer

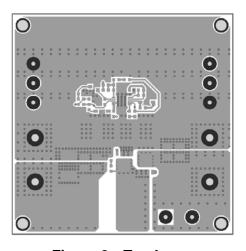


Figure 2—Top Layer

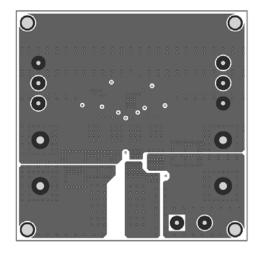


Figure 4—Inner 2 Layer

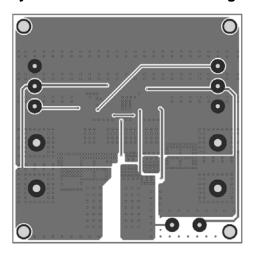


Figure 5—Bottom Layer



## **QUICK START GUIDE**

- 1. Stuff multi-strand wire in VOUT, VOUT GND pad and single strand wire in VIN, VIN GND pad.
- 2. Connect the positive terminal of the load to VOUT multi-strand wire, and the negative terminal of the load to GND multi-strand wire.
- 3. Preset the power supply output to 12V and turn it off.
- 4. Connect the positive terminal of the power supply output to the VIN wire and the negative terminal of the power supply output to the GND wire.
- 5. Connect the EN pin to GND.
- 6. Turn the power supply on. The MP2905EK will automatically startup.
- 7. To use the Enable function, drive EN higher than 4V to turn on the MOS Q3, then SS is pulled down, part shuts down. Drive EN less than 0.5V to turn off the MOS Q3, then SS is released, part turns on. Do not float EN pin.
- 8. The output voltage VOUT can be programmed by R1 and R2. Calculate the new value using the formula:

$$R1 = R2 \times (\frac{V_{OUT}}{V_{FB}} - 1)$$

Where  $V_{FB}$ =0.59V.

In order to get good transient, R1 and R2 should be small enough. Always set R2=1k $\Omega$  or smaller, and R1 is not higher than 3 k $\Omega$ .

9. The frequency is set by C9 and R13. C9 should not be small enough to get good transient response, 2.2nF is recommended, then R13 is used to program the frequency by formula below:

$$R_{13} = \frac{\frac{\text{V}_{\text{out}} \times (\text{V}_{\text{IN}} - \text{V}_{\text{OUT}})}{\text{f}} - \text{V}_{\text{IN}} \times (90 \text{ns} \times \text{V}_{\text{IN}} - 20 \text{ns} \times \text{V}_{\text{OUT}})}{\text{V}_{\text{IN}} \times \text{C}_{9} \times \text{V}_{\text{HY}}}$$

Where V<sub>HY</sub> is output regulation hysteresis, typical value is 22mV.

10. The EV board is designed for 12V input, 1.2Vout application. So, for other application, some parameters such as current limit and frequency need to be redesigned. Please refer to AN023 to set related parameters.

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